

Built in the years '60, this telescope is located at our stellar station at Serra La Nave (mt 1750 asl).

In order to achieve a good level of automation of the pointing system, the original mechanics has been modifyed by our staff.

The original system of a.c. motors and gear-boxes was upgrated with only two brushless motors capable of running, with constant torque, up to 5000 rpm.

The same motor, therefore, allows a positioning of the telescope without jerks by a soft moving, up to a fast speed at the telscope of 1 degree for second.

For both axis of the telescope, the original transission system of endless screw & toothed wheel has been mechanically interfaced with two incremental encoders for a pointing with an accuracy better of 5 arcsec.

The "glue" between mechanics and software is electronics.

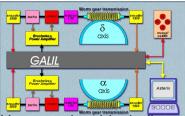
From the *hardware* of motors to the user's interface, the system has four levels of feedback: for the control the speed of the motors, the precision of their speed, their positioning and the position of the whole telescope.



A first level of supervision of the motors is performed by the Servo Amplifier with a *T* achogenerator

An intelligent *motion controller* (by Galil) performs a second and a third level of feedback with a digital control of the speed and the position of the telescope.

The supervising control is done by a Pentium @ 600 MHz Personal Computer. There the Asterix software check the position of the telescope and ensures that the requested star is into the observing field.



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